1A, 1.5MHz Synchronous Step-Down Converter

■ General Description

The AME5253 is a high efficiency monolithic synchronous buck regulator using a constant frequency, current mode architecture. Capable of delivering 1A output current over a wide input voltage range from 2.5V to 5.5V, the AME5253 is ideally suited for single Li-lon battery powered applications. 100% duty cycle provides low dropout operation, extending battery life in portable systems. Under light load conditions, the AME5253 operates in a power saving mode that consumes just around $20\mu A$ of supply current, maximizing battery life in portable applications.

The internal synchronous switch increases efficiency and eliminates the need for an external Schottky diode. Low output voltages are easily supported with the 0.6V feedback reference voltage. The AME5253 is available in SOT-25 package.

Other features include soft start, lower internal reference voltage with 2% accuracy, over temperature protection, and over current protection.

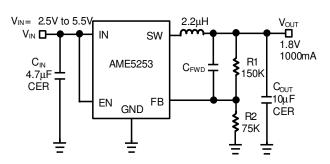
■ Features

- High Efficiency: Up to 95%
- Very Low 20μA Quiescent Current
- High efficiency in light load condition
- 2.5V to 5.5V Input Range
- Adjustable Output From 0.6V to V_{IN}
- 1A Output Current
- Low Dropout Operation: 100% Duty Cycle
- No Schottky Diode Required
- 1.5MHz Constant Frequency PWM Operation
- SOT-25 Packages
- All AME's Lead Free Product Meet RoHS Standard

■ Applications

- Cellular Telephones
- Personal Information Appliances
- Wireless and DSL Modems
- MP3 Players
- Portable Instruments

■ Typical Application



V_{OUT}=V_{FB} (R1+R2)/R2

Figure 1. 1.8V at 1000mA Step-Down Requlator C_{EWD} : 22pF~220pF



■ Function Block Diagram

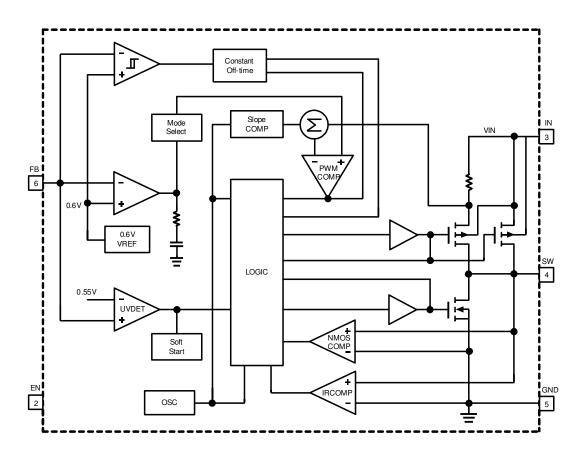
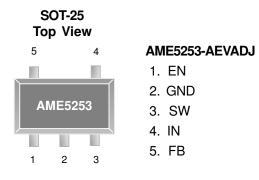


Figure 2. Founction Block Diagram



■ Pin Configuration



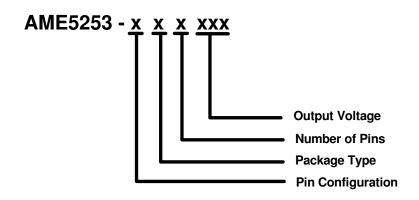
Die Attach: Conductive Epoxy

■ Pin Description

| Pin Number | Pin Name | Pin Description |
|------------|----------|--|
| 1 | EN | No connection. Not internally connected. Can left floating or connected to GND. |
| 2 | GND | Ground. Tie directly to ground plane. |
| 3 | SW | Switch Node Connection to Inductor. |
| 4 | IN | Input Supply Voltage Pin. Bypass this pin with a capacitor as close to the device as possible. |
| 5 | FB | Output voltage Feedback input. |



■ Ordering Information



| Pin Configuration | Package Type | Number of Pins | Output Voltage |
|---|--------------|----------------|-----------------|
| A 1. EN (SOT-25) 2. GND 3. SW 4. IN 5. FB | E: SOT-2X | V: 5 | ADJ: Adjustable |



■ Absolute Maximum Ratings

| Parameter | Symbol | Maximum | Unit |
|------------------------------|-------------------|-------------------------|------|
| Input Supply Voltage | V _{IN} | -0.3 to 6.5 | |
| EN, V _{OUT} Voltage | V_{EN}, V_{OUT} | -0.3 to V _{IN} | V |
| SW Voltage | V _{SW} | -0.3 to V _{IN} | 1 |
| ESD Classification | | B* | |

Caution: Stress above the listed absolute maximum rating may cause permanent damage to the device.

■ Recommended Operating Conditions

| Parameter | Symbol | Rating | Unit |
|----------------------------|----------------|-------------|------|
| Supply Voltage Voltage | V_{IN} | 2.5 to 5.5 | V |
| Ambient Temperature Range | T _A | -40 to +85 | °C |
| Junction Temperature Range | T_J | -40 to +125 | °C |

■ Thermal Information

| Parameter | Package | Die Attach | Symbol | Maximum | Unit |
|--|---------|------------------|----------------------|---------|--------|
| Thermal Resistance* (Junction to Case) | | | $	heta_{	extsf{JC}}$ | 81 | °C / W |
| Thermal Resistance (Junction to Ambient) | SOT-25 | Conductive Epoxy | θ_{JA} | 260 | C / W |
| Internal Power Dissipation | | | P_{D} | 400 | mW |
| Solder Iron (10Sec)** | 350 | °C | | | |

 $^{^{\}star}$ Measure $\;\theta_{\text{JC}}$ on backside center of Exposed Pad.

^{*} HBM B: 2000V~3999V

^{**} MIL-STD-202G 210F



■ Electrical Specifications

 $V_{IN} = 3.6 \text{V}, \ V_{OUT} = 2.5 \text{V}, \ V_{FB} = 0.6 \text{V}, \ L = 2.2 \mu \text{H}, \ C_{IN} = 4.7 \mu \text{F}, \ C_{OUT} = 10 \mu \text{F}, \ T_{A} = 25 ^{\circ} \text{C}, \ I_{MAX} = 1 \text{A unless otherwise specified}.$

| Parameter | Symbol | Test Condition | Min | Тур | Max | Units |
|---|-------------------------|---|----------|------|----------------------|-------|
| Input voltage | V_{IN} | | 2.5 | | 5.5 | V |
| Adjustable Output Range | V_{out} | | V_{FB} | | V _{IN} -0.2 | V |
| Feedback Voltage | V_{FB} | | 0.588 | 0.6 | 0.612 | V |
| Feedback Pin Bias Current | I _{FB} | $V_{FB} = V_{IN}$ | -50 | | 50 | nA |
| Quiescent Current | ΙQ | I _{OUT} =0mA, V _{FB} =1V | | 20 | 35 | μΑ |
| Shutdown Current | I _{SHDN} | V _{EN} =GND | | 0.1 | 1 | μΑ |
| Switch Frequency | f _{OSC} | | 1.2 | 1.5 | 1.8 | MHz |
| High-side Switch On-Resistance | R _{DS,ON, LHI} | I _{SW} =200mA, V _{IN} =3.6V | | 0.28 | | Ω |
| Low-side Switch On-Resistance | R _{DS,ON, LO} | I _{SW} =200mA, V _{IN} =3.6V | | 0.25 | | Ω |
| Switch Current Limit | $I_{SW,CL}$ | V _{IN} =2.5 to 5.5V | 1.4 | 1.6 | | Α |
| EN High (Enabled the Device) ^{Note1} | $V_{EN,HI}$ | V _{IN} =2.5 to 5.5V | 1.5 | | | ٧ |
| EN Low (Shutdown the Device) | $V_{EN,LO}$ | V _{IN} =2.5 to 5.5V | | | 0.4 | V |
| Input Undervoltage Lockout | V _{UVLO} | rising edge | | 1.8 | | V |
| Input Undervoltage Lockout Hysteresis | V _{UVLO,HYST} | | | 0.1 | | V |
| Thermal Shutdown Temperature | ОТР | Shutdown, temperature increasing | | 160 | | °C |
| Maximum Duty Cycle | D _{MAX} | | 100 | | | % |
| SW Leakage Current | | EN=0V, V_{IN} =5.0V V_{SW} =0V or 5.0V | -1 | | 1 | μΑ |

Note1: V_{EN} must be $<= V_{IN}$

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■ Detailed Description

Main Control Loop

AME5253 uses a constant frequency, current mode step-down architecture. Both the main (P-channel MOSFET) and synchronous (N-channel MOSFET) switches are intermal. During normal operation, the internal top power MOSFET is turned on each cycle when the oscillator sets the RS latch, and turned off when the current comparator resets the RS latch. While the top MOSFET is off, the bottom MOSFET is turned on until either the inductor current starts to reverse as indicated by the current reversal comparator IRCMP.

Short-Circuit Protection

When the output is shorted to ground, the frequency of the oscillator is reduced to about 180KHz. This frequency foldback ensures that the inductor current hsa more time do decay, thereby preventing runaway. The oscillator's frequency will progressively increase to 1.5MHz when V_{FB} or V_{OLIT} rises above 0V.

Dropout Operation

As the input supply voltage decreases to a value approaching the output voltage, the duty cycle increases toward the maximum on-time. Further reduction of the supply voltage forces the main switch to remain on for more than one cycle until it reaches 100% duty cycle. The output voltage will then be determined by the input voltage minus the voltage drop across the P-channel MOSFET and the inductor.

■ Application Information

The basic AME5253 application circuit is shown in Typical Application Circuit. External component selection is determined by the maximum load current and begins with the selection of the inductor value and followed by $\mathbf{C}_{\mathbb{N}}$ and $\mathbf{C}_{\mathbb{O}(\mathbb{N})}$.

Inductor Selection

For a given input and output voltage, the inductor value and operating frequency determine the ripple current. The ripple current DIL increases with higher $V_{\rm IN}$ and decreases with higher inductance.

$$\Delta I_L = \frac{1}{(f)(L)} V_{OUT} \left(1 - \frac{V_{OUT}}{V_{IN}} \right)$$

A reasonable starting point for setting ripple current is $\Delta IL=0.4$ (lmax). The DC current rating of the inductor should be at least equal to the maximum load current plus half the ripple current to prevent core saturation. For better efficiency, choose a low DC-resistance inductor.

C_{IN} and C_{OUT} Selection

The input capacitance, C_{IN} is needed to filter the trapezoidal current at the source of the top MOSFET. To prevent large voltage transients, a low ESR input capacitorsized for the maximum RMS current must be used. The maximum RMS capacitor current is given by:

$$I_{\mathit{RMS}} = I_{\mathit{OUT}(\mathit{MAX})} \, \frac{V_{\mathit{OUT}}}{V_{\mathit{IN}}} \, \sqrt{\frac{V_{\mathit{IN}}}{V_{\mathit{OUT}}}} - 1$$

This formula has a maximum at $V_{IN}=2V_{OUT}$, where IRMS= $I_{OUT}/2$. This simple worst-case condition is commonly used for design because even significant deviations do not offer much relief. Note that the capacitor manufacturer ripple current ratings are often based on 2000 hours of life. This makes it advisable to further derate the capacitor, or choose a capacitor rated at a higher temperature than required.

1A, 1.5MHz Synchronous Step-Down Converter

The selection of C_{OUT} is determined by the effective series resistance(ESR) that is required to minimize voltage ripple and load step transients. The output ripple, V_{OUT} , is determined by:

$$\Delta V_{OUT} \cong \Delta I_L \left(ESR + \frac{1}{8 f C_{OUT}} \right)$$

Using Ceramic Input and Output Capacitors

Higher values, lower cost ceramic capacitors are now becoming available in smaller case sizes. Their high ripple current, high voltage rating and low ESR make them ideal for switching regulator applications. However, care must be taken when these capacitors are used at the input and output. When a ceramic capacitor is used at the input and the power is supplied by a wall adapter through long wires, a load step at the output can induce ringing at the input, V_{IN} . At best, this ringing can couple to the output and be mistaken as loop instability. At worst, a sudden inrush of current through the long wires can potentially cause a voltage spike at V_{IN} large enough to damage the part.

Output Voltage Programming

The output voltage is set by an external resistive divider according to the following equation:

$$V_{OUT} = V_{REF} \times \left(1 + \frac{R_1}{R_2}\right)$$

Where VREF equals to 0.6V typical. The resistive divider allows the FB pin to sense a fraction of the output voltage as shown in Figure 3.

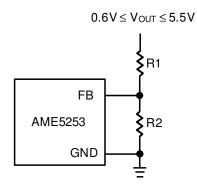


Figure 3. Setting the AME 5253 Output Voltage

Enable

The EN pin provides electrical on/off control of the regulator. When the EN pin voltage exceeds the lockout threshold voltage, the regulator starts to operate.

If the EN pin voltage is pulled below the lockout threshold voltage, the regulator stops switching.

Connecting the EN pin to ground or to any voltage less than 1.5V will disable the regulator and activate the shutdown mode.

The EN pin voltage must be less than or equal to V_{IN} pin voltage. When EN pin voltage more than V_{IN} pin voltage $0.4V \sim 0.7V$.

AME5253 SW pin will be terminated.

Thermal Considerations

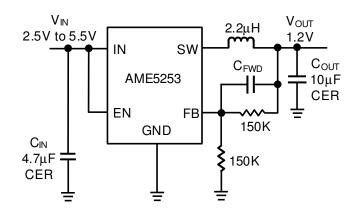
In most applications the AME5253 does not dissipate much heat due to its high efficiency. But, in applications where the AME5253 is running at high ambient temperature with low supply voltage and high duty cycles, such as in dropout, the heat dissipated may exceed the maximum junction temperature of the part. If the junction temperature reaches approximately 160°C, both power switches will be turned off and the SW node will become high impedance. To avoid the AME5253 from exceeding the maximum junction temperature, the user will need to do some thermal analysis. The goal of the thermal analysis is to determine whether the power dissipated exceeds the maximum junction temperature of the part. The temperature rise is given by:

$$T_{R} = (PD)(\theta_{JA})$$

Where PD is the power dissipated by the regulator and θ_{JA} is the thermal resistance from the junction of the die to the ambient temperature.

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AME5253

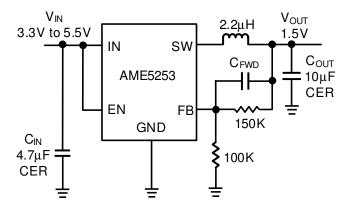


 V_{IN} $V_{\text{OUT}} \\$ 2.2µH 2.7V to 5.5V 2.5V SW IN Cout C_{FWD} AME5253 10μF **CER** ΕN FΒ 150K **GND** C_{IN} $4.7\mu F$ 47.3K **CER**

Figure 4: 1.2V Step-Down Regulator

 C_{FWD} : 22pF~220pF

Figure 7: 2.5V Step-Down Regulator C_{FWD}: 22pF~220pF



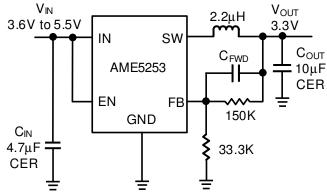


Figure 5: 1.5V Step-Down Regulator C_{FWD}: 22pF~220pF

C_{FWD}: 22pF~220pF

Figure 8: 3.3V Step-Down Regulator

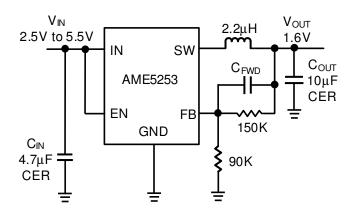


Figure 6: 1.6V Step-Down Regulator

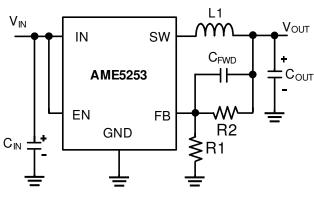
 C_{FWD} : 22pF~220pF

1A, 1.5MHz Synchronous Step-Down Converter

PC Board Layout Checklist

When laying out the printed circuit board, the following checklist should be used to ensure proper operation of the AME5253. These items are also illustrated graphically in Figures 9. Check the following in your layout:

- 1. The power traces, consisting of the GND trace, the SW trace and the V_{IN} trace should be kept short, direct and wide.
- 2. Does the V_{FB} pin connect directly to the feedback resistors? The resistive divider R2/R1 must be connected between the (+) plate of C_{OUT} and ground.
- 3. Does the (+) plate of CIN connect to V_{IN} as closely as possible? This capacitor provides the AC current to the internal power MOSFETs.
- 4. Keep the switching node, SW, away from the sensitive V_{FB} node.
- 5. Keep the (-) plates of $C_{\rm IN}$ and $C_{\rm OUT}$ as close as possible.



Regulator Layout Diagram
CFWD: 22pF~220pF

VIA TO VIN

VIA TO VIA

VIA TO

Figure 9: AME5253 Adjustable Voltage



■ Application Information

External components selection

| Supplier | Inductance (µH) | Current Rating (mA) | DCR (mΩ) | Dimensions (mm) | Series |
|-------------|--------------------|---------------------|-------------|--------------------|----------|
| TAIYO YUDEN | 2.2 | 1480 | 60 | 3.00 x 3.00 x 1.50 | NR 3015 |
| GOTREND | 2.2 | 1500 | 58 | 3.85 x 3.85 x 1.80 | GTSD32 |
| Sumida | 2.2 | 1500 | 75 | 4.50 x 3.20 x 1.55 | CDRH2D14 |
| Sumida | 4.7 | 1000 | 135 | 4.50 x 3.20 x 1.55 | CDRH2D14 |
| TAIYO YUDEN | 4.7 | 1020 | 120 | 3.00 x 3.00 x 1.50 | NR 3015 |
| GOTREND | 4.7 | 1100 | 146 | 3.85 x 3.85 x 1.80 | GTSD32 |

Table 1. Recommended Inductors

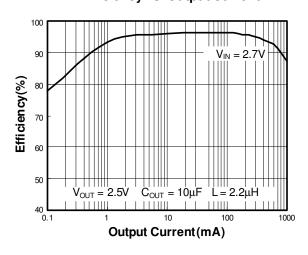
| Supplier | Capacitance (µF) | Package | Part Number |
|-------------|---------------------|---------|-------------------|
| TDK | 4.7 | 603 | C1608JB0J475M |
| MURATA | 4.7 | 603 | GRM188R60J475KE19 |
| TAIYO YUDEN | 4.7 | 603 | JMK107BJ475RA |
| TAIYO YUDEN | 10 | 603 | JMK107BJ106MA |
| TDK | 10 | 805 | C2012JB0J106M |
| MURATA | 10 | 805 | GRM219R60J106ME19 |
| MURATA | 10 | 805 | GRM219R60J106KE19 |
| TAIYO YUDEN | 10 | 805 | JMK212BJ106RD |

Table 2. Recommended Capacitors for $\mathbf{C}_{\text{\tiny{IN}}}$ and $\mathbf{C}_{\text{\tiny{OUT}}}$

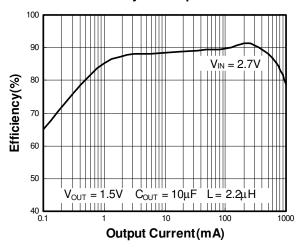


■ Characterization Curve

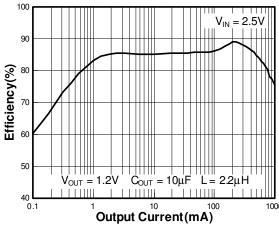
Efficiency vs. Output Current



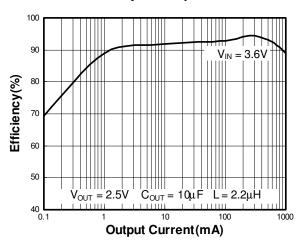
Efficiency vs. Output Current



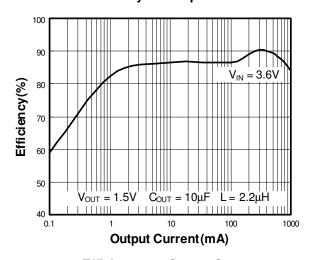
Efficiency vs. Output Current



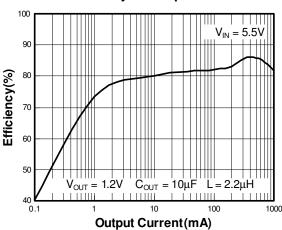
Efficiency vs. Output Current



Efficiency vs. Output Current



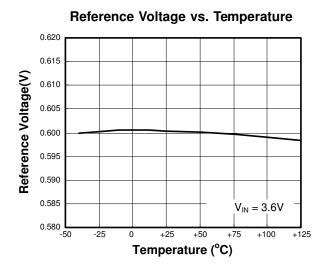
Efficiency vs. Output Current



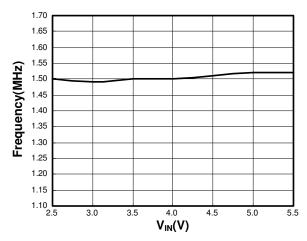




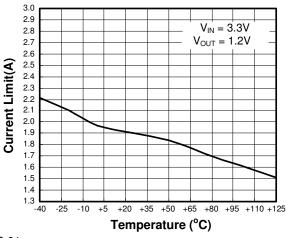
■ Characterization Curve (Contd.)



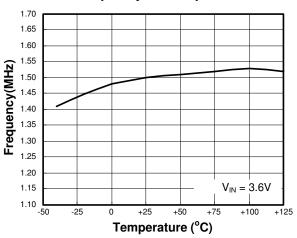
Frequency vs. Supply Voltage



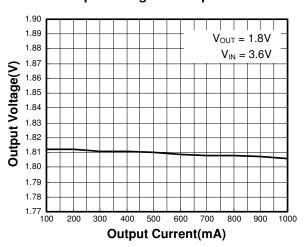
Current Limit vs. Temperature



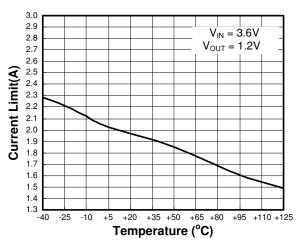
Frequency vs. Temperature



Output Voltage vs. Output Current



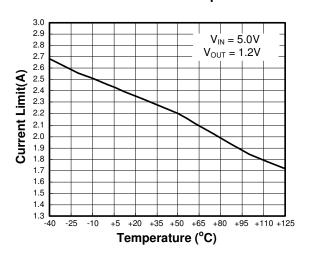
Current Limit vs. Temperature



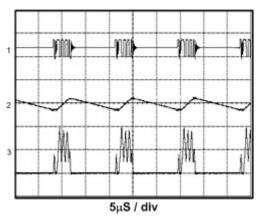


■ Characterization Curve (Contd.)

Current Limit vs. Temperature



Light Load Mode output voltage ripple



$$V_{IN} = 3.6V$$

 $V_{OUT} = 1.8V$
 $I_{OUT} = 50mA$

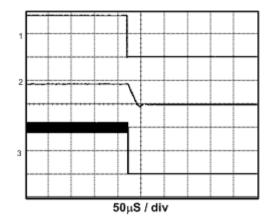
1)
$$V_{sw} = 5V/div$$

1)
$$V_{SW} = 5V/div$$

2) $V_{OUT} = 100 \text{mV/div}$

3)
$$I_1 = 200 \text{mA/div}$$

Power Off from EN



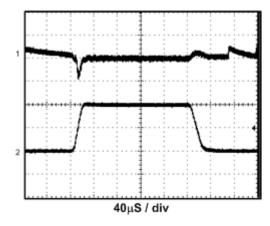
$$V_{IN} = 3.6V$$

 $V_{OUT} = 1.8V$
 $I_{OUT} = 1A$

2)
$$V_{OUT} = 2V/div$$

3)
$$I_1 = 500 \text{mA/div}$$

Load Step



$$V_{IN} = 3.6V$$

 $V_{OUT} = 1.8V$
 $I_{OUT} = 0A \sim 1A \sim 0A$

1)
$$V_{OUT} = 100 \text{mV/div}$$

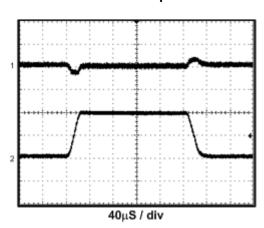
2) $I_{OUT} = 500 \text{mA/div}$

2)
$$I_{OUT} = 500 \text{mA/div}$$



■ Characterization Curve (Contd.)

Load Step



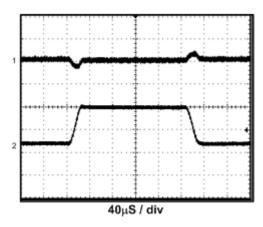
$$V_{IN} = 3.6V$$

 $V_{OUT} = 1.8V$
 $I_{OUT} = 50mA \sim 1A \sim 50mA$

1)
$$V_{OUT} = 100 \text{mV/div}$$

2) $I_{OUT} = 500 \text{mA/div}$

Load Step



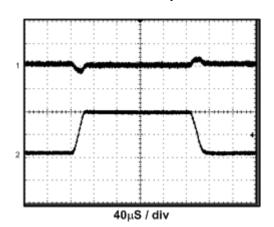
$$V_{IN} = 3.6V$$

 $V_{OUT} = 1.8V$
 $I_{OUT} = 200 \text{mA} \sim 1 \text{A} \sim 200 \text{mA}$

1)
$$V_{OUT} = 100 \text{mV/div}$$

2) $I_{OUT} = 500 \text{mA/div}$

Load Step

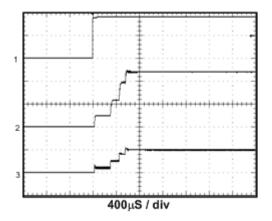


$$V_{IN} = 3.6V$$

 $V_{OUT} = 1.8V$
 $I_{OUT} = 100 \text{mA} \sim 1 \text{A} \sim 100 \text{mA}$

1) $V_{OUT} = 100 \text{mV/div}$ 2) $I_{OUT} = 500 \text{mA/div}$

Power On from EN



$$V_{OUT} = 1.2V$$
 $I_{OUT} = 1A$

1) EN= 2V/div

2) $V_{OUT} = 500 \text{mV/div}$ 3) $I_{L} = 1 \text{A/div}$



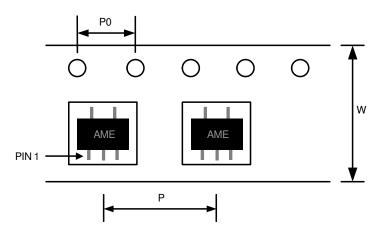
■ Date Code Rule

| Month Code | | | | | |
|-------------|--------------|--|--|--|--|
| 1: January | 7: July | | | | |
| 2: February | 8: August | | | | |
| 3: March | 9: September | | | | |
| 4: April | A: October | | | | |
| 5: May | B: November | | | | |
| 6: June | C: December | | | | |

| | Year | | | | | |
|---|------|----------|---|----------|----------|------|
| Α | Α | Α | М | Χ | Χ | xxx0 |
| Α | Α | Α | М | Χ | <u>X</u> | xxx1 |
| Α | Α | Α | М | <u>X</u> | Χ | xxx2 |
| Α | Α | Α | М | <u>X</u> | <u>X</u> | xxx3 |
| Α | Α | Α | M | Χ | Χ | xxx4 |
| Α | Α | Α | M | Χ | <u>X</u> | xxx5 |
| Α | Α | Α | M | <u>X</u> | Χ | xxx6 |
| Α | Α | Α | M | <u>X</u> | <u>X</u> | xxx7 |
| Α | Α | <u>A</u> | M | Χ | Χ | xxx8 |
| Α | Α | <u>A</u> | М | Χ | <u>X</u> | xxx9 |

■ Tape and Reel Dimension

SOT-25



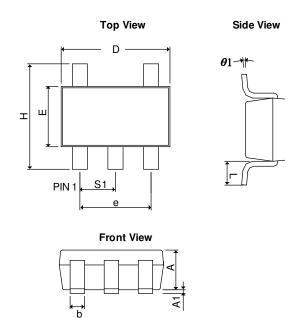
Carrier Tape, Number of Components Per Reel and Reel Size

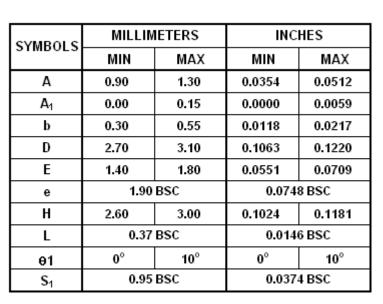
| Package | Carrier Width (W) | Pitch (P) | Pitch (P0) | Part Per Full Reel | Reel Size |
|---------|-------------------|------------|------------|--------------------|-----------|
| SOT-25 | 8.0±0.1 mm | 4.0±0.1 mm | 4.0±0.1 mm | 3000pcs | 180±1 mm |

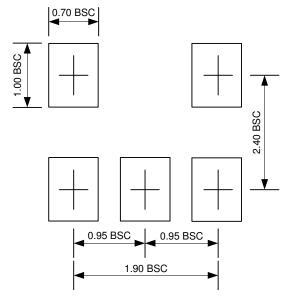


■ Package Dimension

SOT-25







Note:

- 1. Lead pattern unit description:
 - BSC: Basic. Represents theoretical exact dimension or dimension target.
- 2. Dimensions in Millimeters.
- 3. General tolerance 0.05mm unless otherwise specified.



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Life Support Policy:

These products of AME, Inc. are not authorized for use as critical components in life-support devices or systems, without the express written approval of the president of AME, Inc.

AME, Inc. reserves the right to make changes in the circuitry and specifications of its devices and advises its customers to obtain the latest version of relevant information.

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